

# University of Notre Dame Calculus III

## LECTURE 8:

---

### Arc Length and Curvature

In Calc II we found the arc length of a plane curve  $x(t) = f(t)$ ,  $y(t) = g(t)$ ,  $a \leq t \leq b$  as

$$\begin{aligned} L &= \int_a^b \sqrt{[f'(t)]^2 + [g'(t)]^2} dt \\ &= \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt \\ &= \int_a^b \sqrt{dx^2 + dy^2} \end{aligned}$$

This was done by approximating the curve by straight lines. We can do the same thing for curves in  $\mathbb{R}^3$ . This leads to:

**Definition 1.** The arc length of the curve  $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$ ,  $a \leq t \leq b$  is

$$L = \int_a^b \sqrt{[f'(t)]^2 + [g'(t)]^2 + [h'(t)]^2} dt$$

There are some technical assumptions to this formula:

- $\vec{r}'(t)$  is nonzero.
- $f'$ ,  $g'$ , and  $h'$  must be continuous (i.e.  $\vec{r}$  is  $C^1$ )

Notice that because

$$\|\vec{r}'(t)\| = \sqrt{[f'(t)]^2 + [g'(t)]^2 + [h'(t)]^2}$$

we have that the arc length can be computed as

$$L = \int_a^b \|\vec{r}'(t)\| dt$$

**Example 1.** Find the arc length of

$$\vec{r}(t) = \langle t, 3 \cos t, 3 \sin t \rangle$$

where  $-5 \leq t \leq 5$ .

**Solution:**

A curve  $C$  need not have a unique representation by a vector function, in fact, none do. For example  $\vec{r}_1(t) = \langle t, t^2, t^3 \rangle$ ,  $1 \leq t \leq 2$  is also represented by  $\vec{r}_2(u) = \langle e^u, e^{2u}, e^{3u} \rangle$ ,  $0 \leq u \leq 2$ .  $\vec{r}_1$  and  $\vec{r}_2$  are called parametrizations of  $C$ . There is one particular parametrization we care about, and it is found as follows: Suppose  $C$  is given by  $\vec{r}(t)$ ,  $a \leq t \leq b$ , with  $\vec{r}'$  continuous and  $\vec{r}(t)$  traverses  $C$  exactly once. We can define the arc length function

$$s(t) = \int_a^t \|\vec{r}'(u)\| du$$

which tells us the distance traveled at time  $t$ . Now, suppose we can solve this equation for  $t$  in terms of  $s$ . In other words invert  $s(t)$  so that  $t = t(s)$ . Then:

**Definition 2.** The Arc Length Reparametrization of  $\vec{r}(t)$  is

$$\vec{r} = \vec{r}(t(s)), \quad 0 \leq s \leq L$$

where  $L = \text{arc length of } \vec{r} \text{ from } t = a \text{ to } t = b$ .

**Example 2.** Reparametrize  $\vec{r}(t) = \langle t, 3 \cos t, 3 \sin t \rangle$ ,  $-5 \leq t \leq 5$  with respect to arc length.

**Solution:**

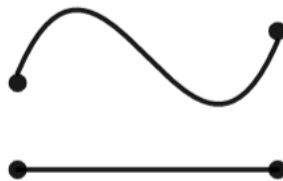
An interesting fact about arc length reparametrizations:

$$\frac{d\vec{r}}{ds} = \frac{d}{ds}(\vec{r}(t(s))) = \left(\frac{dt}{ds}\right) \vec{r}'(t(s)) = \frac{1}{\|\vec{r}'(t)\|} \vec{r}'(t(s))$$

So,  $\left\| \frac{d\vec{r}}{ds} \right\| = 1$ , that is, arc length reparametrizations always move with unit speed!

## Curvature

Intuitively, curvature is a measure of how sharply a curve bends. Pictorially, the curved line has larger curvature than the bottom line does:



**Definition 3.** A parametrization  $\vec{r}(t)$  is called smooth on an interval  $I$  if  $\vec{r}'$  is continuous on  $I$  and  $\vec{r}'(t) \neq \vec{0}$  for any  $t \in I$ . A curve  $C$  is called smooth if it has a smooth parametrization.

We quantify curvature as the rate of change of the unit tangent vector with respect to arc length. In symbols, the curvature of  $\vec{r}$  is

$$\kappa = \left\| \frac{d\vec{T}}{ds} \right\|$$

Now  $\frac{d\vec{T}}{ds}$  can often be messy to compute, however, we have a trick: by the chain rule

$$\frac{d\vec{T}}{dt} = \frac{d\vec{T}}{ds} \frac{ds}{dt} = \frac{d\vec{T}}{ds} \|\vec{r}'(t)\|$$

So, a more convenient formula for curvature is

$$\kappa = \frac{\|\vec{T}'(t)\|}{\|\vec{r}'(t)\|}$$

**Example 3.** Find the curvature of a circle of radius  $a$ .

**Solution:**

Even that formula is more effort than needed. Another is

$$\kappa(t) = \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^3}$$

**Example 4.** Find the curvature of  $\vec{r}(t) = \langle \sqrt{2}t, e^t, e^{-t} \rangle$  at  $(0, 1, 1)$ .

**Solution:**

---

In the special case of a plane curve  $y = f(x)$ , by parametrizing it as  $\vec{r}(x) = \langle x, f(x) \rangle$  we get

$$\kappa(x) = \frac{|f''(x)|}{(1 + [f'(x)]^2)^{3/2}} .$$

### Frenet-Serret Frame "T - N - B Frame"

This consists of 3 vectors derived from a parametrization,  $\vec{r}(t)$ :  $\vec{T}(t)$ ,  $\vec{N}(t)$ , and  $\vec{B}(t)$ . We already know one of them, the other two are

Unit Normal Vector (Requiring  $\|\vec{T}'(t)\| \neq 0$ , equivalently  $\kappa(t) \neq 0$ )

$$\vec{N}(t) = \frac{\vec{T}'(t)}{\|\vec{T}'(t)\|}$$

Binormal Vector

$$\vec{B}(t) = \vec{T}(t) \times \vec{N}(t)$$

Since  $\|\vec{T}(t)\| = 1$ , we have  $\vec{T}(t) \cdot \vec{T}'(t) = 0$ , so  $\vec{T} \perp \vec{N}$ . By definition of  $\times$ ,  $\vec{B} \perp \vec{T}$ ,  $\vec{N}$ , so the three vectors are all orthogonal to each other. Thus since  $\|\vec{T}\| = \|\vec{N}\| = 1$ , we have  $\|\vec{B}\| = \|\vec{T} \times \vec{N}\| = \|\vec{T}\| \|\vec{N}\| \sin \frac{\pi}{2} = 1$ , thus all of  $\vec{T}$ ,  $\vec{N}$ , and  $\vec{B}$  and hard to compute, so here's an alternate way:

$$\vec{B}(t) = \frac{\vec{r}'(t) \times \vec{r}''(t)}{\|\vec{r}'(t) \times \vec{r}''(t)\|} \quad \vec{N}(t) = \vec{B}(t) \times \vec{T}(t).$$

$\vec{N}$  always points in the direction the curve is bending and  $\vec{B}$  points orthogonal to the motion of the curve.

We can create some planes using  $\vec{T}$ ,  $\vec{N}$ , and  $\vec{B}$ .

Normal Plane: This plane is perpendicular to  $\vec{r}(t)$ . It is determined by  $\vec{N}$  and  $\vec{B}$ , and so has  $\vec{T}$  as a vector orthogonal to it.

Osculating Plane: This plane best captures the motion of the curve. It is determined by  $\vec{T}$  and  $\vec{N}$ , and so has  $\vec{B}$  as a vector perpendicular to it.

Rectifying Plane: This plane determined by  $\vec{T}$  and  $\vec{B}$ . We won't bother with this one.

---

**Example 5.** Find  $\vec{T}(t)$ ,  $\vec{N}(t)$ , and  $\vec{B}(t)$  for  $\vec{r}(t) = \langle t, 3 \cos t, 3 \sin t \rangle$  and find equations for the normal and osculating planes at  $(\pi/2, 0, 3)$ .

**Solution:**

A comment on the normal and osculating planes:

Recall that we only need a vector which is perpendicular to the plane to find an equation for it, in particular, the length of the vector doesn't matter. So, easier vectors to use are:

Normal Plane: use  $\vec{r}'(t)$

Osculating Plane: use  $\vec{r}'(t) \times \vec{r}''(t)$

### Extra Examples

1. Find an integral to evaluate the length of the curve  $\mathbf{r}(t) = \langle \cos t, \sin t, t^2 \rangle$  as  $t$  varies between 0 and  $2\pi$ .
2. A particle has position  $\mathbf{r}(t) = \langle t - \frac{2}{3}t^3, t^2, 2t \rangle$  at time  $t$ . Find an integral to evaluate the distance traveled by the particle as it moves from  $(0, 0, 0)$  to  $(\frac{1}{3}, 1, 2)$ .
3. Let  $C$  be the curve given by the vector function  $\mathbf{r}(t) = \langle 1 - \frac{1}{2}t^2, t, t^2 \rangle$ . Find the equation of the osculating plane to  $C$  at the point  $(1, 0, 0)$ .
4. For the curve  $\mathbf{r}(t) = \langle t^2, \frac{2}{3}t^3, t \rangle$ . Find the vectors  $\mathbf{T}, \mathbf{N}, \mathbf{B}$  at the point  $(1, \frac{2}{3}, 1)$ . Also find equations of the normal and osculating planes at the same point.